

# Generalized Orthogonal Matching Pursuit- A Review and Some New Results

Mrityunjoy Chakraborty

Department of Electronics and Electrical Communication  
Engineering Indian Institute of Technology,  
Kharagpur, INDIA

## 1 Overview of Compressed Sensing (CS)

- 1 Overview of Compressed Sensing (CS)
  - Basic CS Formulation.

- 1 Overview of Compressed Sensing (CS)
  - Basic CS Formulation.
  - CS Reconstruction Methods.

- 1 Overview of Compressed Sensing (CS)
  - Basic CS Formulation.
  - CS Reconstruction Methods.
  
- 2 Generalized Orthogonal Matching Pursuit (gOMP)

- 1 Overview of Compressed Sensing (CS)
  - Basic CS Formulation.
  - CS Reconstruction Methods.
  
- 2 Generalized Orthogonal Matching Pursuit (gOMP)
  - Algorithm Discussion.

- 1 Overview of Compressed Sensing (CS)
  - Basic CS Formulation.
  - CS Reconstruction Methods.
  
- 2 Generalized Orthogonal Matching Pursuit (gOMP)
  - Algorithm Discussion.
  - Performance Analysis.

- 1 Overview of Compressed Sensing (CS)
  - Basic CS Formulation.
  - CS Reconstruction Methods.
  
- 2 Generalized Orthogonal Matching Pursuit (gOMP)
  - Algorithm Discussion.
  - Performance Analysis.
  
- 3 References



## Overview of Compressed Sensing (CS)

# Overview of Compressed Sensing (CS)

- A powerful technique to represent signals at a sub-Nyquist sampling rate, provided the signal is known to be sparse in some domain.

# Overview of Compressed Sensing (CS)

- A powerful technique to represent signals at a sub-Nyquist sampling rate, provided the signal is known to be sparse in some domain.
- It retains the capacity of perfect (or near perfect) reconstruction of the signal from fewer samples than provided by Nyquist rate sampling.

# Overview of Compressed Sensing (CS)

- A powerful technique to represent signals at a sub-Nyquist sampling rate, provided the signal is known to be sparse in some domain.
- It retains the capacity of perfect (or near perfect) reconstruction of the signal from fewer samples than provided by Nyquist rate sampling.
- In last few years, the CS technique has attracted considerable attention from across a wide array of fields like

# Overview of Compressed Sensing (CS)

- A powerful technique to represent signals at a sub-Nyquist sampling rate, provided the signal is known to be sparse in some domain.
- It retains the capacity of perfect (or near perfect) reconstruction of the signal from fewer samples than provided by Nyquist rate sampling.
- In last few years, the CS technique has attracted considerable attention from across a wide array of fields like
  - 1 applied mathematics,
  - 2 statistics, and
  - 3 engineering including signal processing areas like
    - (i) MR imaging,
    - (ii) speech processing,
    - (iii) analog to digital conversion etc.

## Basic CS Formulation:

- Let a real valued, bandlimited signal  $u(t)$  be sampled following Nyquist sampling rate condition and over a finite observation interval, generating the observation vector:

$$\mathbf{u} = (u_1, u_2, \dots, u_N)^T.$$

## Basic CS Formulation:

- Let a real valued, bandlimited signal  $u(t)$  be sampled following Nyquist sampling rate condition and over a finite observation interval, generating the observation vector:  
$$\mathbf{u} = (u_1, u_2, \dots, u_N)^T.$$
- Further,  $\mathbf{u}$  is known to be sparse in some transform domain  
 $\Rightarrow$  if  $\Psi$ : The  $N \times N$  transform matrix (usually unitary) and,  
 $\mathbf{x}$ : Transform coefficient vector ( $\in \mathbb{R}^N$ ), so that  
$$\mathbf{u} = \Psi \mathbf{x},$$

## Basic CS Formulation:

- Let a real valued, bandlimited signal  $u(t)$  be sampled following Nyquist sampling rate condition and over a finite observation interval, generating the observation vector:  
$$\mathbf{u} = (u_1, u_2, \dots, u_N)^T.$$
- Further,  $\mathbf{u}$  is known to be sparse in some transform domain  
 $\Rightarrow$  if  $\Psi$ : The  $N \times N$  transform matrix (usually unitary) and,  
 $\mathbf{x}$ : Transform coefficient vector ( $\in \mathbb{R}^N$ ), so that  
$$\mathbf{u} = \Psi \mathbf{x},$$

then,  $\mathbf{x}$  is  $K$ -sparse

$\Rightarrow$  a maximum of  $K$  no. of terms in  $\mathbf{x}$  are non-zero.



# Overview of CS (Cont.)

- Then, according to the CS theory, it is possible to recover  $\mathbf{u}$  from a fewer no., say,  $M$  ( $M < N$ ) samples:  $y_1, y_2, \dots, y_M$ , linearly related to  $u_1, u_2, \dots, u_N$  as  $\mathbf{y} = \mathbf{A}\mathbf{u} = \mathbf{\Phi}\mathbf{x}$ , ( $\mathbf{\Phi} = \mathbf{A}\mathbf{\Psi}$ ) where,  $\mathbf{y} = [y_1, y_2, \dots, y_M]^T$ , and  $\mathbf{A}$ : A  $M \times N$  sensing matrix.

# Overview of CS (Cont.)

- Then, according to the CS theory, it is possible to recover  $\mathbf{u}$  from a fewer no., say,  $M$  ( $M < N$ ) samples:  $y_1, y_2, \dots, y_M$ , linearly related to  $u_1, u_2, \dots, u_N$  as  $\mathbf{y} = \mathbf{A}\mathbf{u} = \mathbf{\Phi}\mathbf{x}$ , ( $\mathbf{\Phi} = \mathbf{A}\mathbf{\Psi}$ ) where,  
 $\mathbf{y} = [y_1, y_2, \dots, y_M]^T$ , and  
 $\mathbf{A}$ : A  $M \times N$  sensing matrix.
- Ideal approach to recover  $\mathbf{x}$  is by  $l_0$  minimization:

$$\min_{\mathbf{x} \in \mathbb{R}^N} \|\mathbf{x}\|_0 \quad \text{subject to } \mathbf{y} = \mathbf{\Phi}\mathbf{x}. \quad (1)$$

- It provides the sparsest solution for  $\mathbf{x}$ .
- Uniqueness of the  $K$ -sparse solution requires that every  $2K$  columns of  $\mathbf{\Phi}$  should be linearly independent.

# Overview of CS (Cont.)

- Then, according to the CS theory, it is possible to recover  $\mathbf{u}$  from a fewer no., say,  $M$  ( $M < N$ ) samples:  $y_1, y_2, \dots, y_M$ , linearly related to  $u_1, u_2, \dots, u_N$  as  $\mathbf{y} = \mathbf{A}\mathbf{u} = \mathbf{\Phi}\mathbf{x}$ , ( $\mathbf{\Phi} = \mathbf{A}\mathbf{\Psi}$ ) where,  $\mathbf{y} = [y_1, y_2, \dots, y_M]^T$ , and  $\mathbf{A}$ : A  $M \times N$  sensing matrix.
- Ideal approach to recover  $\mathbf{x}$  is by  $l_0$  minimization:

$$\min_{\mathbf{x} \in \mathbb{R}^N} \|\mathbf{x}\|_0 \quad \text{subject to } \mathbf{y} = \mathbf{\Phi}\mathbf{x}. \quad (1)$$

- It provides the sparsest solution for  $\mathbf{x}$ .
  - Uniqueness of the  $K$ -sparse solution requires that every  $2K$  columns of  $\mathbf{\Phi}$  should be linearly independent.
- But, it is a non-convex problem and is NP-hard.

## Overview of CS (Cont.)

- More practical approaches using  $l_1$  norm (and above) can find the desired  $K$ -sparse solution.
  - But this requires  $\Phi$  to satisfy certain “Restricted Isometry Property (RIP)”.

# Overview of CS (Cont.)

- More practical approaches using  $l_1$  norm (and above) can find the desired  $K$ -sparse solution.
  - But this requires  $\Phi$  to satisfy certain “Restricted Isometry Property (RIP)”.
- A matrix  $\Phi$  is said to satisfy the RIP of order  $K$  if there exists a “Restricted Isometry Constant”  $\delta_K \in (0, 1)$  so that

$$(1 - \delta_K) \|\mathbf{x}\|_2^2 \leq \|\Phi\mathbf{x}\|_2^2 \leq (1 + \delta_K) \|\mathbf{x}\|_2^2 \quad (2)$$

for all  $K$ -sparse  $\mathbf{x}$ .

# Overview of CS (Cont.)

- More practical approaches using  $l_1$  norm (and above) can find the desired  $K$ -sparse solution.
  - But this requires  $\Phi$  to satisfy certain “Restricted Isometry Property (RIP)”.
- A matrix  $\Phi$  is said to satisfy the RIP of order  $K$  if there exists a “Restricted Isometry Constant”  $\delta_K \in (0, 1)$  so that

$$(1 - \delta_K) \|\mathbf{x}\|_2^2 \leq \|\Phi\mathbf{x}\|_2^2 \leq (1 + \delta_K) \|\mathbf{x}\|_2^2 \quad (2)$$

for all  $K$ -sparse  $\mathbf{x}$ .

- The constant  $\delta_K$  is taken as the smallest number from  $(0, 1)$  for which the RIP is satisfied.

# Overview of CS (Cont.)

- More practical approaches using  $l_1$  norm (and above) can find the desired  $K$ -sparse solution.
  - But this requires  $\Phi$  to satisfy certain “Restricted Isometry Property (RIP)”.
- A matrix  $\Phi$  is said to satisfy the RIP of order  $K$  if there exists a “Restricted Isometry Constant”  $\delta_K \in (0, 1)$  so that

$$(1 - \delta_K) \|\mathbf{x}\|_2^2 \leq \|\Phi\mathbf{x}\|_2^2 \leq (1 + \delta_K) \|\mathbf{x}\|_2^2 \quad (2)$$

for all  $K$ -sparse  $\mathbf{x}$ .

- The constant  $\delta_K$  is taken as the smallest number from  $(0, 1)$  for which the RIP is satisfied.
- If  $\Phi$  satisfies RIP of order  $K$ , then it also satisfies RIP for any order  $L$  where  $L < K$  and that  $\delta_L \geq \delta_K$ .

# Overview of CS (Cont.)

- More practical approaches using  $l_1$  norm (and above) can find the desired  $K$ -sparse solution.
  - But this requires  $\Phi$  to satisfy certain “Restricted Isometry Property (RIP)”.

- A matrix  $\Phi$  is said to satisfy the RIP of order  $K$  if there exists a “Restricted Isometry Constant”  $\delta_K \in (0, 1)$  so that

$$(1 - \delta_K) \|\mathbf{x}\|_2^2 \leq \|\Phi\mathbf{x}\|_2^2 \leq (1 + \delta_K) \|\mathbf{x}\|_2^2 \quad (2)$$

for all  $K$ -sparse  $\mathbf{x}$ .

- The constant  $\delta_K$  is taken as the smallest number from  $(0, 1)$  for which the RIP is satisfied.
- If  $\Phi$  satisfies RIP of order  $K$ , then it also satisfies RIP for any order  $L$  where  $L < K$  and that  $\delta_L \geq \delta_K$ .
- Simple choice of random matrices for  $\Phi$  can make it satisfy RIP with high probability.



## CS Reconstruction Methods

## CS Reconstruction Methods

Convex Relaxation:

## CS Reconstruction Methods

Convex Relaxation:

- It replaces the  $l_0$  norm in (1) by  $l_1$  norm to reduce the problem to a convex problem.

## CS Reconstruction Methods

Convex Relaxation:

- It replaces the  $l_0$  norm in (1) by  $l_1$  norm to reduce the problem to a convex problem.
- Three main directions under this category, namely the basis pursuit (BP), the basis pursuit de-noising (BPDN) and the least absolute shrinkage and selection operator (LASSO):

$$1. \text{ BP: } \min_{\mathbf{x} \in \mathbb{R}^N} \|\mathbf{x}\|_1 \text{ subject to } \mathbf{y} = \Phi \mathbf{x} \quad (3)$$

$$2. \text{ BPDN: } \min_{\mathbf{x} \in \mathbb{R}^N} \lambda \|\mathbf{x}\|_1 + \|\mathbf{r}\|_2^2 \text{ s.t. } \mathbf{r} = \mathbf{y} - \Phi \mathbf{x} \quad (4)$$

$$3. \text{ LASSO: } \min_{\mathbf{x} \in \mathbb{R}^N} \|\mathbf{y} - \Phi \mathbf{x}\|_2^2 \text{ s.t. } \|\mathbf{x}\|_1 \leq \epsilon \quad (5)$$

## Overview of CS (Cont.)

- The BP problem can be solved by standard polynomial time algorithms of linear programming (LP) methods.

## Overview of CS (Cont.)

- The BP problem can be solved by standard polynomial time algorithms of linear programming (LP) methods.
- The exact  $K$ -sparse signal reconstruction by BP algorithm based on RIP was first investigated by E. Candès et.al. (2006) with the following bound on  $\delta_K$

$$\delta_K + \delta_{2K} + \delta_{3K} < 1 \quad (6)$$

## Overview of CS (Cont.)

- The BP problem can be solved by standard polynomial time algorithms of linear programming (LP) methods.
- The exact  $K$ -sparse signal reconstruction by BP algorithm based on RIP was first investigated by E. Candès et.al. (2006) with the following bound on  $\delta_K$

$$\delta_K + \delta_{2K} + \delta_{3K} < 1 \quad (6)$$

- Later the bound was refined by S. Foucart (2010) as  $\delta_{2K} < 0.4652$ .

## Overview of CS (Cont.)

- The BP problem can be solved by standard polynomial time algorithms of linear programming (LP) methods.
- The exact  $K$ -sparse signal reconstruction by BP algorithm based on RIP was first investigated by E. Candès et.al. (2006) with the following bound on  $\delta_K$

$$\delta_K + \delta_{2K} + \delta_{3K} < 1 \quad (6)$$

- Later the bound was refined by S. Foucart (2010) as  $\delta_{2K} < 0.4652$ .
- The BPDN and LASSO problems can be solved by efficient quadratic programming (QP) like primal-dual interior method.



## Overview of CS (Cont.)

- The BP problem can be solved by standard polynomial time algorithms of linear programming (LP) methods.
- The exact  $K$ -sparse signal reconstruction by BP algorithm based on RIP was first investigated by E. Candès et.al. (2006) with the following bound on  $\delta_K$

$$\delta_K + \delta_{2K} + \delta_{3K} < 1 \quad (6)$$

- Later the bound was refined by S. Foucart (2010) as  $\delta_{2K} < 0.4652$ .
- The BPDN and LASSO problems can be solved by efficient quadratic programming (QP) like primal-dual interior method.
- However, the regularization parameters  $\lambda$  and  $\epsilon$  play a crucial role in the performance of these algorithms.

# Overview of CS (Cont.)

## Greedy Pursuits:

- This approach recovers the  $K$ -sparse signal by iteratively constructing the support set of the sparse signal (index of non-zero elements in the sparse vector).

# Overview of CS (Cont.)

## Greedy Pursuits:

- This approach recovers the  $K$ -sparse signal by iteratively constructing the support set of the sparse signal (index of non-zero elements in the sparse vector).
- At each iteration, it updates its support set by appending the index of one or more columns (called atoms) of the matrix  $\Phi$  (often called dictionary) by some greedy principles based on the correlation between current residual of observation vector and the atoms.

## Greedy Pursuits:

- Few examples of greedy algorithms:

- 1 Orthogonal Matching Pursuit (OMP):  $\delta_{K+1} < \frac{1}{\sqrt{2K}}$
- 2 Compressive Sampling Matching Pursuit (CoSaMP):  $\delta_{4K} < 0.1$
- 3 Subspace Pursuit (SP):  $\delta_{3K} < 0.165$
- 4 Iterative Hard Thresholding (IHT):  $\delta_{3K} < \frac{1}{\sqrt{32}} \approx 0.177$ .
- 5 Generalized Orthogonal Matching Pursuit (gOMP):  
 $\delta_{NK} < \frac{\sqrt{N}}{\sqrt{K+3\sqrt{N}}}$  where  $N(\geq 1)$  is the number of atoms selected by the gOMP algorithm in each iteration [1].

## Overview of CS (Cont.)

- OMP reconstructs the  $K$ -sparse signal in  $K$  steps by selecting one atom in each iteration.

## Overview of CS (Cont.)

- OMP reconstructs the  $K$ -sparse signal in  $K$  steps by selecting one atom in each iteration.
- CoSaMP and SP select a fixed number of atoms ( $2K$  in CoSaMP and  $K$  in SP, for  $K$ -sparse signal) in each iteration while keeping the provision of rejecting a previously selected atom.

## Overview of CS (Cont.)

- OMP reconstructs the  $K$ -sparse signal in  $K$  steps by selecting one atom in each iteration.
- CoSaMP and SP select a fixed number of atoms ( $2K$  in CoSaMP and  $K$  in SP, for  $K$ -sparse signal) in each iteration while keeping the provision of rejecting a previously selected atom.
- IHT uses gradient descent followed by a hard thresholding that sets all but the  $K$  largest (in magnitude) elements in a vector to zero.

# Generalized Orthogonal Matching Pursuit (gOMP)



# Generalized Orthogonal Matching Pursuit (gOMP)

- The generalized orthogonal matching pursuit (gOMP) is a generalization of orthogonal matching pursuit (OMP).

# Generalized Orthogonal Matching Pursuit (gOMP)

- The generalized orthogonal matching pursuit (gOMP) is a generalization of orthogonal matching pursuit (OMP).
- In contrast to the OMP algorithm, the gOMP algorithm reconstructs the  $K$ -sparse signal in  $K$  steps by selecting  $N(> 1)$  atoms in each iteration.

# Generalized Orthogonal Matching Pursuit (Cont.)

Table: gOMP algorithm

---

**Input:** measurement  $\mathbf{y} \in \mathbb{R}^m$ , sensing matrix  $\Phi^{m \times n}$

**Initialization:** counter  $k=0$ , residue  $\mathbf{r}^0 = \mathbf{y}$ ,  
estimated support set  $\Lambda^k = \emptyset$

---

**While**  $k < K$  and  $\|\mathbf{r}^k\|_2 > 0$

*Identification:*  $h^{k+1}$  = Set of indices corresponding to the  $N$  largest entries in  $|\Phi^t \mathbf{r}^k|$ . ( $NK \leq m$ )

*Augment:*  $\Lambda^{k+1} = \Lambda^k \cup \{h^{k+1}\}$

*Estimate:*  $\mathbf{x}_{\Lambda^{k+1}} = \arg \min_{\mathbf{z}} \|\mathbf{y} - \Phi_{\Lambda^{k+1}} \mathbf{z}\|_2$

*Update:*  $\mathbf{r}^{k+1} = \mathbf{y} - \Phi_{\Lambda^{k+1}} \mathbf{x}_{\Lambda^{k+1}}$

$k = k + 1$

**End While**

**Output:**  $\mathbf{x} = \arg \min_{\mathbf{u}: \text{supp}(\mathbf{u}) = \Lambda^k} \|\mathbf{y} - \Phi \mathbf{u}\|_2$

---

# Generalized Orthogonal Matching Pursuit (Cont.)

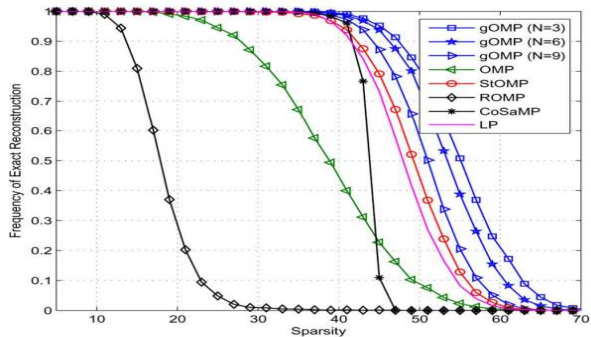


Figure: Reconstruction performance for  $K$ -sparse Gaussian signal vector using Gaussian dictionary ( $128 \times 256$ ) as a function of sparsity  $K$

Courtesy: J. Wang, S. Kwon & B. Shim (2012) [1]

# Generalized Orthogonal Matching Pursuit (Cont.)

**Analysis of the gOMP algorithm by J. Wang, S. Kwon & B. Shim (2012):**

# Generalized Orthogonal Matching Pursuit (Cont.)

## Analysis of the gOMP algorithm by J. Wang, S. Kwon & B. Shim (2012):

- In gOMP algorithm, convergence in a maximum of  $K$  steps is established by ensuring that in each iteration, at least one of the  $N$  new atoms chosen belongs to  $\Phi_T$ , i.e., it has an index belonging to the true support set  $T$ .

# Generalized Orthogonal Matching Pursuit (Cont.)

## Analysis of the gOMP algorithm by J. Wang, S. Kwon & B. Shim (2012):

- In gOMP algorithm, convergence in a maximum of  $K$  steps is established by ensuring that in each iteration, at least one of the  $N$  new atoms chosen belongs to  $\Phi_T$ , i.e., it has an index belonging to the true support set  $T$ .
- Let  $\beta^{k+1}$ ,  $k = 0, 1, \dots, K - 1$  denote the largest (in magnitude) correlation between  $\mathbf{r}^k$  and the atoms of  $\Phi_T$  at the  $k$ -th step of iteration, i.e.,  
$$\beta^{k+1} = \max\{|\phi_i^t \mathbf{r}^k| \mid i \in T, k = 0, 1, \dots, K - 1\}.$$

# Generalized Orthogonal Matching Pursuit (Cont.)

## Analysis of the gOMP algorithm by J. Wang, S. Kwon & B. Shim (2012):

- In gOMP algorithm, convergence in a maximum of  $K$  steps is established by ensuring that in each iteration, at least one of the  $N$  new atoms chosen belongs to  $\Phi_T$ , i.e., it has an index belonging to the true support set  $T$ .
- Let  $\beta^{k+1}$ ,  $k = 0, 1, \dots, K - 1$  denote the largest (in magnitude) correlation between  $\mathbf{r}^k$  and the atoms of  $\Phi_T$  at the  $k$ -th step of iteration, i.e.,  
$$\beta^{k+1} = \max\{|\phi_i^t \mathbf{r}^k| \mid i \in T, k = 0, 1, \dots, K - 1\}.$$
- Let the  $N$  largest (in magnitude) correlations between  $\mathbf{r}^k$  and the atoms of  $\Phi$  not belonging to  $\Phi_T$  be given by  $\alpha_i^{k+1}$ ,  $i = 1, 2, \dots, N$ , arranged in descending order as  $\alpha_1^{k+1} > \alpha_2^{k+1} \dots > \alpha_N^{k+1}$ .



# Generalized Orthogonal Matching Pursuit (Cont.)

**Analysis of the gOMP algorithm by J. Wang, S. Kwon & B. Shim (2012):**

Then, it is shown in [1] that

# Generalized Orthogonal Matching Pursuit (Cont.)

**Analysis of the gOMP algorithm by J. Wang, S. Kwon & B. Shim (2012):**

Then, it is shown in [1] that



$$\alpha_N^{k+1} < \frac{1 - 3\delta_{NK}}{1 - \delta_{NK}} \frac{\|\mathbf{x}_{T-\Lambda^k}\|_2}{\sqrt{N}} \quad (7)$$

# Generalized Orthogonal Matching Pursuit (Cont.)

**Analysis of the gOMP algorithm by J. Wang, S. Kwon & B. Shim (2012):**

Then, it is shown in [1] that



$$\alpha_N^{k+1} < \frac{1 - 3\delta_{NK}}{1 - \delta_{NK}} \frac{\|\mathbf{x}_{T-\Lambda^k}\|_2}{\sqrt{N}} \quad (7)$$

and



$$\beta^{k+1} > \frac{\delta_{NK}}{1 - \delta_{NK}} \frac{\|\mathbf{x}_{T-\Lambda^k}\|_2}{\sqrt{K-l}}, \quad (8)$$

where  $l = |T \cap \Lambda^k|$ .

# Generalized Orthogonal Matching Pursuit (Cont.)

**Analysis of the gOMP algorithm by J. Wang, S. Kwon & B. Shim (2012):**

Then, it is shown in [1] that



$$\alpha_N^{k+1} < \frac{1 - 3\delta_{NK}}{1 - \delta_{NK}} \frac{\|\mathbf{x}_{T-\Lambda^k}\|_2}{\sqrt{N}} \quad (7)$$

and



$$\beta^{k+1} > \frac{\delta_{NK}}{1 - \delta_{NK}} \frac{\|\mathbf{x}_{T-\Lambda^k}\|_2}{\sqrt{K-l}}, \quad (8)$$

where  $l = |T \cap \Lambda^k|$ .

- Therefore, the sufficient condition to ensure convergence in a maximum of  $K$  steps is then obtained by setting the RHS of (8) greater than that of (7) as

$$\delta_{NK} < \frac{\sqrt{N}}{\sqrt{K+3\sqrt{N}}} \text{ where } N(\geq 1)$$

# Generalized Orthogonal Matching Pursuit (Cont.)

Our (i.e. with **R. L. Das** & **S. Satpathi**) contribution:

# Generalized Orthogonal Matching Pursuit (Cont.)

**Our (i.e. with R. L. Das & S. Satpathi) contribution:**

- We first retain the upper bound of  $\alpha_N^{k+1}$  as given in (2), while the lower bound of  $\beta^{k+1}$  given in (3) is refined which eventually results in a lesser restrictive upper bound on  $\delta_{NK}$  as shown in Theorem 1.

## Our (i.e. with **R. L. Das & S. Satpathi**) contribution:

- We first retain the upper bound of  $\alpha_N^{k+1}$  as given in (2), while the lower bound of  $\beta^{k+1}$  given in (3) is refined which eventually results in a lesser restrictive upper bound on  $\delta_{NK}$  as shown in Theorem 1.
- Subsequently, we refine both the upper bound of  $\alpha_N^{k+1}$  and the lower bound of  $\beta^{k+1}$ , which leads to an improved upper bound on  $\delta_{NK+1}$  as shown Theorem 2.

# Generalized Orthogonal Matching Pursuit (Cont.)

The derivation uses the following Lemma, which is an extension of the Lemma 3.2 of [11].

## Lemma 1

Given  $\mathbf{u} \in \mathbb{R}^n$ ,  $I_1, I_2 \subset Z$  where  $I_2 = \text{supp}(\mathbf{u})$  and  $I_1 \cap I_2 = \emptyset$

$$\left(1 - \frac{\delta_{|I_1|+|I_2|}}{1 - \delta_{|I_1|+|I_2|}}\right) \|\mathbf{u}\|_2^2 \leq \|\mathbf{A}_{I_1} \mathbf{u}\|_2^2 \leq (1 + \delta_{|I_1|+|I_2|}) \|\mathbf{u}\|_2^2$$



# Generalized Orthogonal Matching Pursuit (Cont.)

Additionally, we use certain properties of the RIP constant, given by Lemma 1 in [7],[8] which are reproduced below.

## Lemma 2

For  $I, J \subset Z, I \cap J = \emptyset, \mathbf{q} \in \mathbb{R}^{|I|}$  and  $\mathbf{p} \in \mathbb{R}^{|J|}$

(a)  $\delta_{K_1} \leq \delta_{K_2} \forall K_1 < K_2$  (monotonicity)

(b)  $(1 - \delta_{|I|})\|\mathbf{q}\|_2 \leq \|\Phi_I^t \Phi_I \mathbf{q}\|_2 \leq (1 + \delta_{|I|})\|\mathbf{q}\|_2$

(c)  $\langle \Phi_I \mathbf{q}, \Phi_J \mathbf{p} \rangle \leq \delta_{|I|+|J|}\|\mathbf{p}\|_2\|\mathbf{q}\|_2$  with equality holding if either of  $\mathbf{p}$  and  $\mathbf{q}$  is zero. Also,  $\|\Phi_J^t \Phi_J \mathbf{p}\|_2 \leq \delta_{|I|+|J|}\|\mathbf{p}\|_2$  with equality holding if  $\mathbf{p}$  is zero.

# Generalized Orthogonal Matching Pursuit (Cont.)

The Theorem 1:

## Theorem 1

The gOMP can recover  $\mathbf{x}$  exactly when  $\Phi$  satisfies RIP of order  $NK$  with

$$\delta_{NK} < \frac{\sqrt{N}}{\sqrt{K} + 2\sqrt{N}}$$

# Generalized Orthogonal Matching Pursuit (Cont.)

The Theorem 1:

## Theorem 1

The gOMP can recover  $\mathbf{x}$  exactly when  $\Phi$  satisfies RIP of order  $NK$  with

$$\delta_{NK} < \frac{\sqrt{N}}{\sqrt{K} + 2\sqrt{N}}$$

## Proof.

We have shown in [12] that

$$\beta^{k+1} > \frac{1}{\sqrt{K}} \left(1 - \frac{\delta_{NK}}{1 - \delta_{NK}}\right) \|\mathbf{x}_{T-\Lambda^k}\|_2 \quad (9)$$

Setting the RHS of (9) greater than the RHS of (7), the result follows trivially. □

► For Complete Proof of Theorem 1

# Generalized Orthogonal Matching Pursuit (Cont.)

The Theorem 2:

## Theorem 2

*The gOMP algorithm can recover  $\mathbf{x}$  exactly when  $\Phi$  satisfies RIP of order  $NK + 1$  with*

$$\delta_{NK+1} < \frac{\sqrt{N}}{\sqrt{K} + \sqrt{N}}$$

# Generalized Orthogonal Matching Pursuit (Cont.)

Proof.

Note that  $\mathbf{r}^k = \mathbf{P}_{\Lambda^k}^\perp \mathbf{y} = \mathbf{P}_{\Lambda^k}^\perp \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k}$ . We can then write,

$$\mathbf{r}^k = \Phi_{T \cup \Lambda^k} \mathbf{x}_{T \cup \Lambda^k}'' \quad (10)$$

where

$$\mathbf{x}_{T \cup \Lambda^k}'' = \begin{bmatrix} \mathbf{x}_{T-\Lambda^k} \\ -\mathbf{z}_{\Lambda^k} \end{bmatrix} \quad (11)$$

and  $\mathbf{P}_{\Lambda^k} \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k} = \Phi_{\Lambda^k} \mathbf{z}_{\Lambda^k}$  for some  $\mathbf{z}_{\Lambda^k} \in \mathbb{R}^{|\Lambda^k|} \equiv \mathbb{R}^{N_k}$ .

Then, it is shown in [12] that  $\alpha_N^{k+1} < \frac{1}{\sqrt{N}} \delta_{N_{k+1}} \|\mathbf{x}_{T \cup \Lambda^k}''\|_2$  and  $\beta^{k+1} > \frac{1}{\sqrt{K}} (1 - \delta_{N_k}) \|\mathbf{x}_{T \cup \Lambda^k}''\|_2$ . Setting the RHS of (11) greater than that of (10), the result is obtained trivially.  $\square$

▶ For Complete Proof of Theorem 2

▶ Go to references

# Proof of Theorem 1 in detail

First note that  $\beta^{k+1} = \|\Phi_T^t \mathbf{r}^k\|_\infty$ ,  $k = 0, 1, \dots, K-1$  and that  $\mathbf{r}^k = \mathbf{P}_{\Lambda^k}^\perp \mathbf{y}$  is orthogonal to each column of  $\Phi_{\Lambda^k}$ , which also means that  $\mathbf{P}_{\Lambda^k}^\perp \mathbf{y} = \mathbf{P}_{\Lambda^k}^\perp \Phi_T \mathbf{x}_T$   
 $= \mathbf{P}_{\Lambda^k}^\perp (\Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k} + \Phi_{T \cap \Lambda^k} \mathbf{x}_{T \cap \Lambda^k}) = \mathbf{P}_{\Lambda^k}^\perp \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k}$ . It is then possible to write,

$$\begin{aligned} \beta^{k+1} &= \|\Phi_T^t \mathbf{r}^k\|_\infty > \frac{1}{\sqrt{K}} \|\Phi_T^t \mathbf{r}^k\|_2 \text{ (as } |T| = K) \\ &= \frac{1}{\sqrt{K}} \|\Phi_{T-\Lambda^k}^t \mathbf{r}^k\|_2 = \frac{1}{\sqrt{K}} \|\Phi_{T-\Lambda^k}^t \mathbf{P}_{\Lambda^k}^\perp \mathbf{y}\|_2 \\ &= \frac{1}{\sqrt{K}} \|\Phi_{T-\Lambda^k}^t (\mathbf{P}_{\Lambda^k}^\perp)^t \mathbf{P}_{\Lambda^k}^\perp \mathbf{y}\|_2 \text{ (as } \mathbf{P} = \mathbf{P}^t \& \mathbf{P} = \mathbf{P}^2) \\ &= \frac{1}{\sqrt{K}} \|(\mathbf{P}_{\Lambda^k}^\perp \Phi_{T-\Lambda^k})^t \mathbf{P}_{\Lambda^k}^\perp \Phi_T \mathbf{x}_T\|_2 \\ &= \frac{1}{\sqrt{K}} \|(\mathbf{P}_{\Lambda^k}^\perp \Phi_{T-\Lambda^k})^t \mathbf{P}_{\Lambda^k}^\perp \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k}\|_2 \end{aligned} \tag{12}$$

# Proof of Theorem 1 in detail I

Next we define a vector  $\mathbf{x}'$ , where  $x'_i = x_i$  if  $i \in T - \Lambda^k$  and  $x'_i = 0$  otherwise. It is easy to see that  $\Phi \mathbf{x}' = \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k}$  and thus,

$$\mathbf{A}_{\Lambda^k} \mathbf{x}' = \mathbf{P}_{\Lambda^k}^\perp \Phi \mathbf{x}' = \mathbf{P}_{\Lambda^k}^\perp \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k}. \quad (13)$$

[It is also easy to observe that  $\mathbf{P}_{\Lambda^k}^\perp \Phi \mathbf{x}' = \mathbf{P}_{\Lambda^k}^\perp \Phi_T \mathbf{x}_T = \mathbf{r}^k$ , since  $\mathbf{P}_{\Lambda^k}^\perp \phi_i = \mathbf{0}$  for  $i \in \Lambda^k$ .] We are now in a position to apply Lemma 1 on  $\mathbf{A}_{\Lambda^k} \mathbf{x}'$ , taking  $l_1 = \Lambda^k$  and  $l_2 = \text{supp}(\mathbf{x}') = T - \Lambda^k$  and noting that  $l_1 \cap l_2 = \emptyset$ ,  $|l_1| + |l_2| = Nk + K - l$ , to obtain

$$\begin{aligned} \|\mathbf{A}_{\Lambda^k} \mathbf{x}'\|_2^2 &\geq \left(1 - \frac{\delta_{Nk+K-l}}{1 - \delta_{Nk+K-l}}\right) \|\mathbf{x}'\|_2^2 \\ &\stackrel{L1a}{>} \left(1 - \frac{\delta_{Nk}}{1 - \delta_{Nk}}\right) \|\mathbf{x}_{T-\Lambda^k}\|_2^2, \end{aligned} \quad (14)$$

# Proof of Theorem 1 in detail II

where  $Nk + K - l < NK$  follows from the fact that  $k \leq l$  and  $k < K$ . Moreover,

$$\begin{aligned} & \|\mathbf{A}_{\Lambda^k} \mathbf{x}'\|_2^2 \stackrel{(13)}{=} \|\mathbf{P}_{\Lambda^k}^\perp \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k}\|_2^2 \\ &= \langle \mathbf{P}_{\Lambda^k}^\perp \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k}, \mathbf{P}_{\Lambda^k}^\perp \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k} \rangle \\ &= \langle (\mathbf{P}_{\Lambda^k}^\perp \Phi_{T-\Lambda^k})^t P_{\Lambda^k}^\perp \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k}, \mathbf{x}_{T-\Lambda^k} \rangle \\ &\leq \|(\mathbf{P}_{\Lambda^k}^\perp \Phi_{T-\Lambda^k})^t P_{\Lambda^k}^\perp \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k}\|_2 \|\mathbf{x}_{T-\Lambda^k}\|_2 \end{aligned} \quad (15)$$

Combining (14) and (15) we get  $\|(\mathbf{P}_{\Lambda^k}^\perp \Phi_{T-\Lambda^k})^t P_{\Lambda^k}^\perp \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k}\|_2 > (1 - \frac{\delta_{NK}}{1 - \delta_{NK}}) \|\mathbf{x}_{T-\Lambda^k}\|_2$ .

From (12), it then follows that

$$\beta^{k+1} > \frac{1}{\sqrt{K}} \left(1 - \frac{\delta_{NK}}{1 - \delta_{NK}}\right) \|\mathbf{x}_{T-\Lambda^k}\|_2 \quad (16)$$

Setting the RHS of (16) greater than the RHS of (7), the result follows trivially.



# Proof of Theorem 2 in detail

First, as seen earlier,  $\mathbf{r}^k = \mathbf{P}_{\Lambda^k}^\perp \mathbf{y} = \mathbf{P}_{\Lambda^k}^\perp \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k}$ . We can then write,

$$\begin{aligned}\mathbf{r}^k &= \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k} - \mathbf{P}_{\Lambda^k} \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k} \\ &= \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k} - \Phi_{\Lambda^k} \mathbf{z}_{\Lambda^k} \\ &= \Phi_{T \cup \Lambda^k} \mathbf{x}''_{T \cup \Lambda^k}\end{aligned}\tag{17}$$

where we use the fact that  $\mathbf{P}_{\Lambda^k} \Phi_{T-\Lambda^k} \mathbf{x}_{T-\Lambda^k}$  belongs to the  $\text{span}(\Phi_{\Lambda^k})$  and thus can be written as  $\Phi_{\Lambda^k} \mathbf{z}_{\Lambda^k}$  for some  $\mathbf{z}_{\Lambda^k} \in \mathbb{R}^{|\Lambda^k|} \equiv \mathbb{R}^{N_k}$ . The vector  $\mathbf{x}''_{T \cup \Lambda^k}$  is then given as,

$$\mathbf{x}''_{T \cup \Lambda^k} = \begin{bmatrix} \mathbf{x}_{T-\Lambda^k} \\ -\mathbf{z}_{\Lambda^k} \end{bmatrix}\tag{18}$$

# Proof of Theorem 2 in detail I

Let  $W$  be the set of  $N$  incorrect indices corresponding to  $\alpha_i^{k+1}$ 's for  $i = 1, 2, \dots, N$  (clearly,  $W \subset (T \cup \Lambda^k)^c$  and  $|W| = N$ ). So,

$$\begin{aligned}\alpha_N^{k+1} &= \min(\|\langle \Phi_i, \mathbf{r}^k \rangle\| \mid i \in W) \\ &\leq \frac{\|\Phi_W^t \mathbf{r}^k\|_2}{\sqrt{N}} \quad (\text{as } |W| = N) \\ (17) \quad &= \frac{1}{\sqrt{N}} \|\Phi_W^t \Phi_{T \cup \Lambda^k} \mathbf{x}''_{T \cup \Lambda^k}\|_2 \\ &\stackrel{L2c}{\leq} \frac{1}{\sqrt{N}} \delta_{N+Nk+K-1} \|\mathbf{x}''_{T \cup \Lambda^k}\|_2 \\ &\stackrel{L2a}{<} \frac{1}{\sqrt{N}} \delta_{NK+1} \|\mathbf{x}''_{T \cup \Lambda^k}\|_2\end{aligned} \tag{19}$$

where  $N + Nk + K - 1 < NK + 1$  follows from the fact that  $l \geq k$  and  $k \leq K - 1$ .

Similarly,

$$\begin{aligned} \beta^{k+1} &= \|\Phi_T^t \mathbf{r}^k\|_\infty \geq \frac{1}{\sqrt{K}} \|\Phi_T^t \mathbf{r}^k\|_2 \quad (\text{as } |T| = K) \\ &= \frac{1}{\sqrt{K}} \|\left[\Phi_T \quad \Phi_{\Lambda^k - T}\right]^t \mathbf{r}^k\|_2 \end{aligned} \quad (20)$$

$$\begin{aligned} &= \frac{1}{\sqrt{K}} \|\Phi_{T \cup \Lambda^k}^t \Phi_{T \cup \Lambda^k} \mathbf{x}''_{T \cup \Lambda^k}\|_2 \\ &\stackrel{L2b}{>} \frac{1}{\sqrt{K}} (1 - \delta_{N_{k+K-1}}) \|\mathbf{x}''_{T \cup \Lambda^k}\|_2 \\ &\stackrel{L12a}{>} \frac{1}{\sqrt{K}} (1 - \delta_{NK}) \|\mathbf{x}''_{T \cup \Lambda^k}\|_2. \end{aligned} \quad (21)$$

Setting the RHS of (21) greater than that of (19), the result is obtained trivially.

## References

- 1 J. Wang, S. Kwon, and B. Shim, "Generalized orthogonal matching pursuit," *IEEE Trans. Signal Processing*, vol. 60, no. 12, pp. 6202-6216, Dec. 2012.
- 2 D.L. Donoho, "Compressed sensing", *IEEE Trans. Information Theory*, vol. 52, no. 4, pp. 1289-1306, Apr., 2006.
- 3 R. Baraniuk, "Compressive sensing", *IEEE Signal Processing Magazine*, vol. 25, pp. 21-30, March, 2007.
- 4 J.A. Tropp, and A.C. Gilbert, "Signal recovery from random measurements via orthogonal matching pursuit", *IEEE Trans. Information Theory*, vol. 53, no. 12, pp. 4655-4666, Dec., 2007.

- 5 J. A. Tropp and S. J. Wright, “Computational methods for sparse solution of linear inverse problems,” *Proc. IEEE*, vol. 98, no. 6, pp. 948-958, June, 2010.
- 6 S. Chen, S. A. Billings, and W. Luo, “Orthogonal least squares methods and their application to non-linear system identification”, *Int. J. Contr.*, vol. 50, no. 5, pp. 1873-1896, 1989.
- 7 D. Needell and J. Tropp, “CoSaMP : Iterative Signal Recovery from Incomplete and Inaccurate Samples”, *Appl. Comput. Harmon. Anal.*, vol. 26, pp. 301-321, 2009.
- 8 W. Dai and O. Milenkovic, “Subspace Pursuit for Compressive Sensing Signal Reconstruction”, *IEEE Trans. Information Theory*, vol. 55, no. 5, pp. 2230-2249, 2009.

- 9 M. Elad, *Sparse and Redundant Representations*, Springer, 2010.
- 10 J. Wang and B. Shim, "On the recovery limit of sparse signals using orthogonal matching pursuit," *IEEE Trans. Signal Processing*, vol. 60, no. 9, pp. 4973-4976, sept. 2012.
- 11 M. A. Davenport and M. B. Wakin, "Analysis of Orthogonal Matching Pursuit Using the Restricted Isometry Property", *IEEE Trans. Information Theory*, vol. 56, no. 9, pp. 4395-4401, Sept., 2010.
- 12 S. Satpathi, R. L. Das and M. Chakraborty, "Improved Bounds on RIP for Generalized Orthogonal Matching Pursuit", *arXiv:1302.0490*, 2013.

# Thanks!